The background of the slide is a nighttime photograph of a cityscape. A prominent feature is a large, illuminated bridge with a tall, curved pylon and multiple stay cables, extending across the right side of the frame. The bridge is lit with a warm, yellowish light. In the foreground, there are silhouettes of trees and a small pavilion-like structure. The sky is dark, and the overall scene is lit with a mix of warm and cool tones.

WGAN-GP

application on radar reflectivity nowcasting

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Outline

- ◆ Introduction
- ◆ Methodology
- ◆ Results
- ◆ Summary
- ◆ Future work
- ◆ Reference

Introduction

The issues of extrapolation nowcasting are

- ◇ Weather system may growth and decay
- ◇ Can we save more time after a system after it detected by radar?

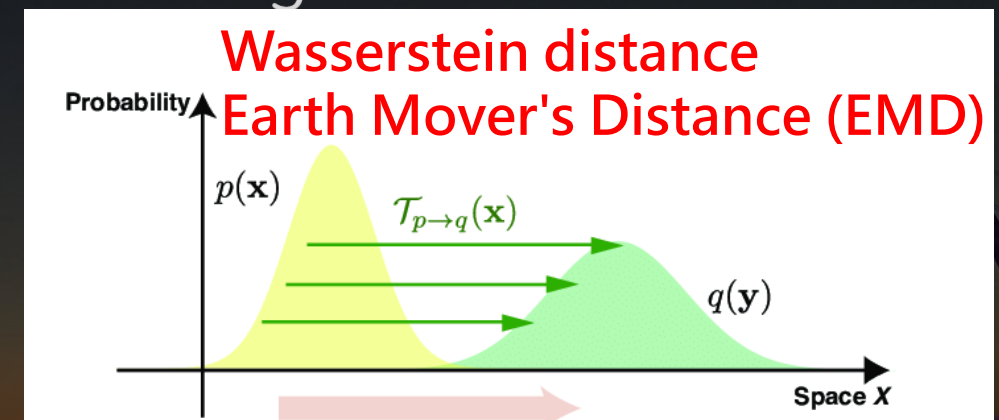
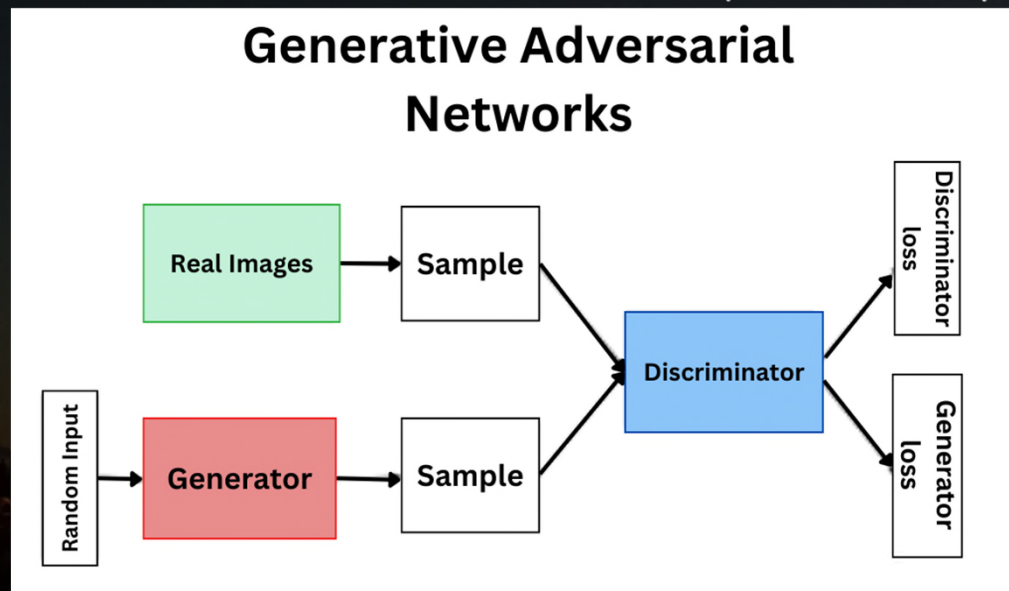
→ Deep learning may be a solution



Methodology

WGAN

- ◇ GAN = Generative Adversarial Network
- ◇ Generator → generate “fake” radar images
- ◇ Discriminator → discriminate image is fake or true
- ◇ Wasserstein GAN (WGAN) solve the gradient vanish



<https://medium.com/@sumit.kaul.87/what-is-generative-adversarial-networks-gans-32e747b03f46>

Methodology

WGAN

- ◇ Training discriminator every steps
- ◇ Training generator every 5 steps



Methodology

Discriminator - Convolutional Neural Network (CNN)

Convolve

1 _{x1}	1 _{x0}	1 _{x1}	0	0
0 _{x0}	1 _{x1}	1 _{x0}	1	0
0 _{x1}	0 _{x0}	1 _{x1}	1	1
0	0	1	1	0
0	1	1	0	0

Image

4		

Convolved
Feature

Max pooling

Single depth slice

x	1	1	2	4
	5	6	7	8
	3	2	1	0
	1	2	3	4
	y			

max pool with 2x2 filters
and stride 2

6	8
3	4

Methodology

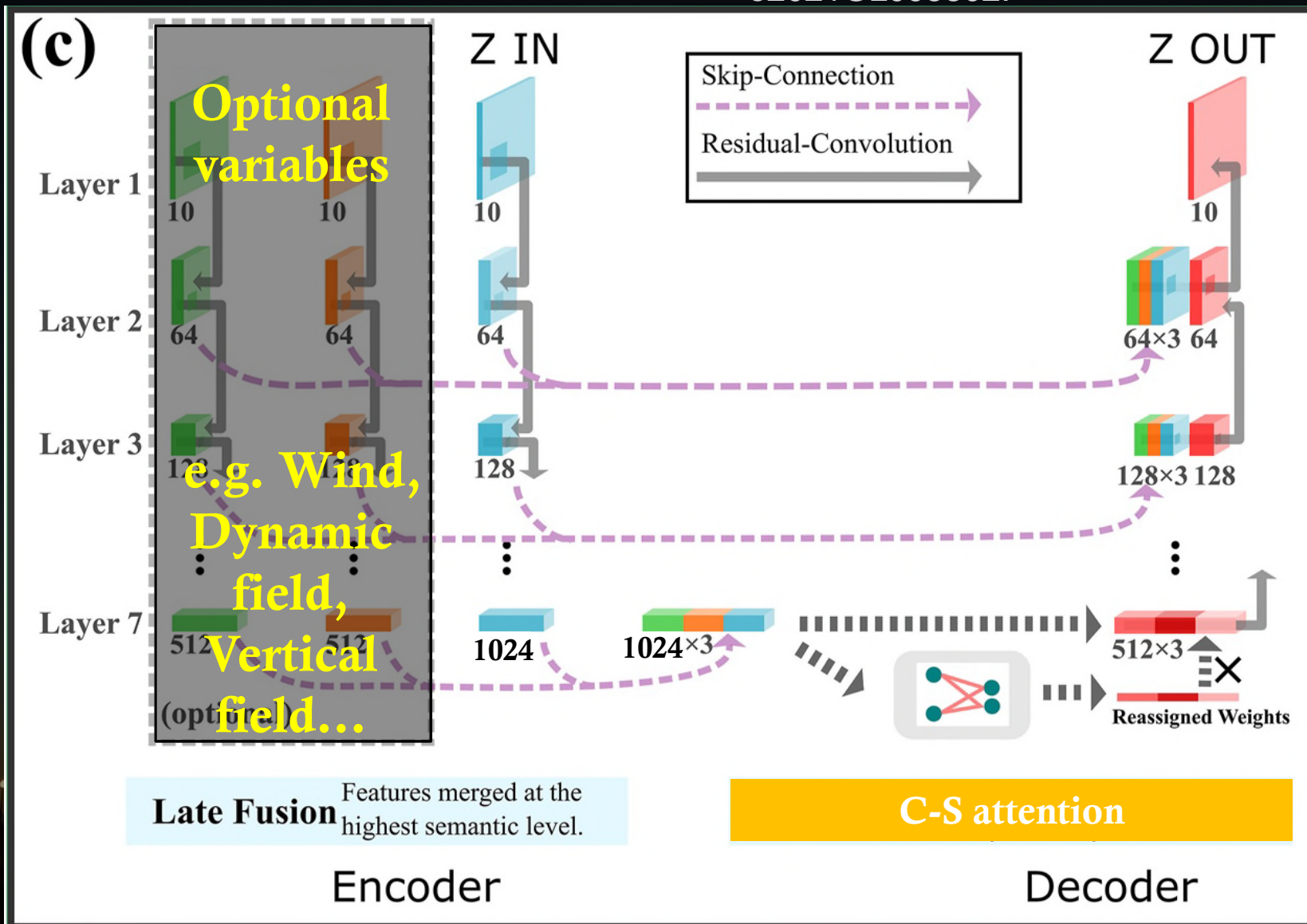
Generator - U-Net

Pan, X., Lu, Y., Zhao, K., Huang, H., Wang, M., & Chen, H. (2021). Improving Nowcasting of convective development by incorporating polarimetric radar variables into a deep-learning model. *Geophysical Research Letters*, 48(21), e2021GL095302.

Local Features



Global Features



Local Features

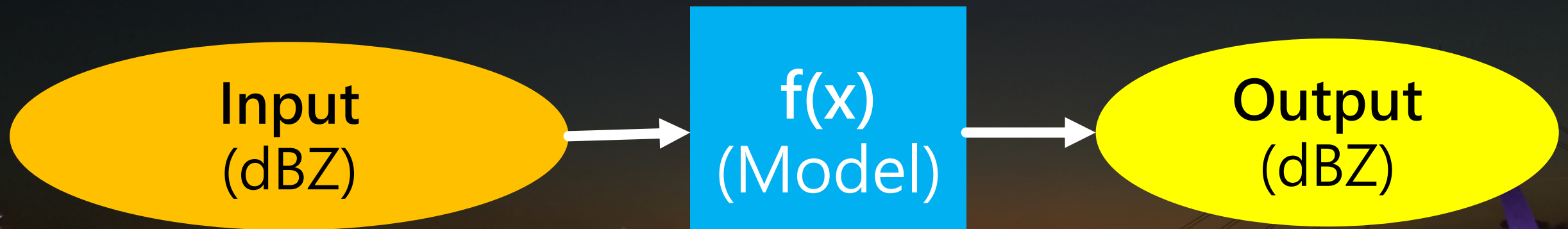


Global Features

Methodology

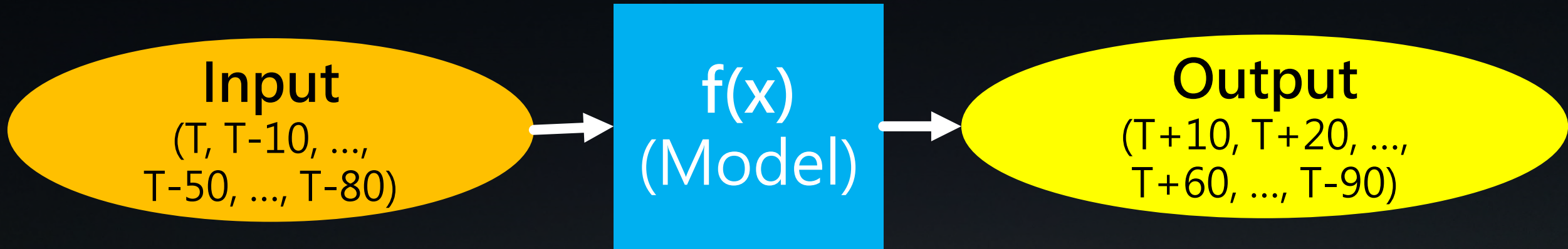
Data & Hyperparameter

- ◆ Source: CWA QPESUMS radar composite reflectivity (dBZ)
- ◆ Training & validation: 2021 OND ~ 2022 JFM each 10 minutes
- ◆ Evaluation: 2022 OND ~ 2023 JFM each 10 minutes
- ◆ Learning rate (size of steps in gradient descent): 10^{-3}



Methodology

Data & Hyperparameter



- ◇ 10 minutes gap between each input and output
- ◇ Input 6 or 9 radar images (T, T-10, ..., T-50, ..., T-80)
- ◇ Output 6 or 9 radar images (T+10, T+20, ..., T+60, ..., T-90)

Methodology

Clear sky threshold

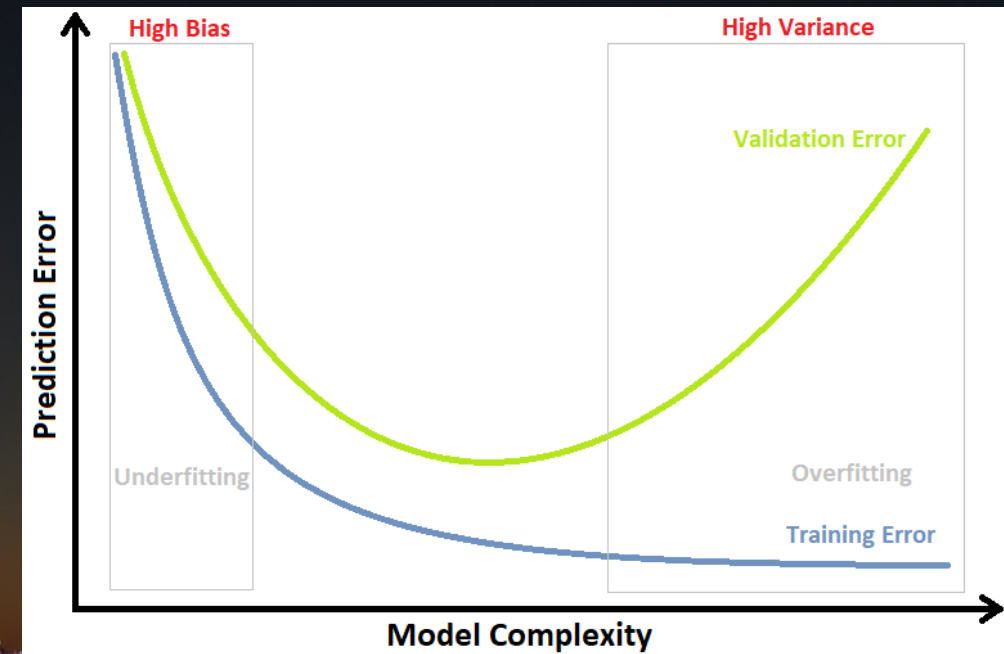
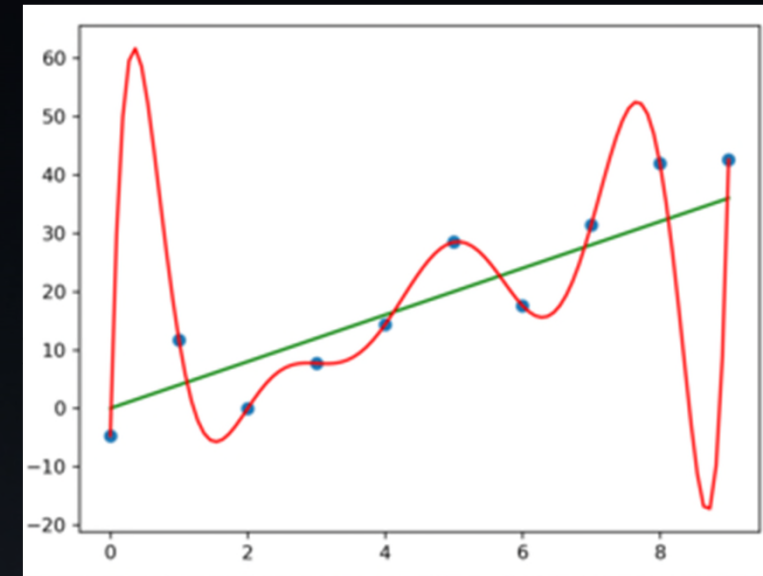
- ◆ Too much clear sky in the training set will cause unbalance and bias (Lin et al. 2024)
- ◆ Use percentage of 15 dBZ area filter out clear sky data
- ◆ All models train 45 epochs

15 dBZ area threshold	Number of orininal data	Number of filtered data
10 %	25829	2903
15 %	25829	1884
20 %	25829	1244

Methodology

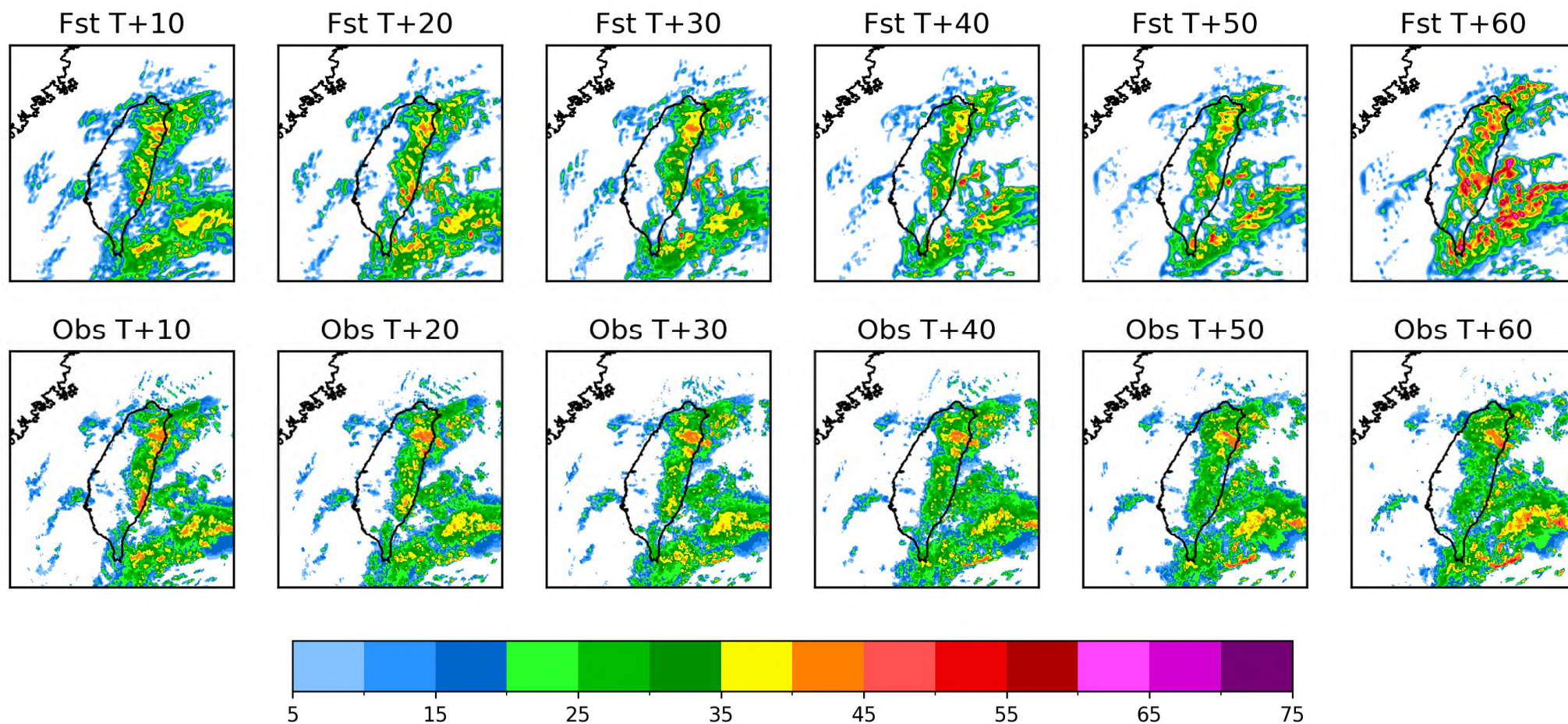
Cross-validation

- ◆ Overfitting: model fit too closely to training data
→ Good on training data but not other data
- ◆ Cross-validation: Randomly split 70% data into "training-set" and 30% into "validation-set". Use "validation loss" to determine when stop training
- ◆ If validation loss stop improve over 20 epochs, stop training



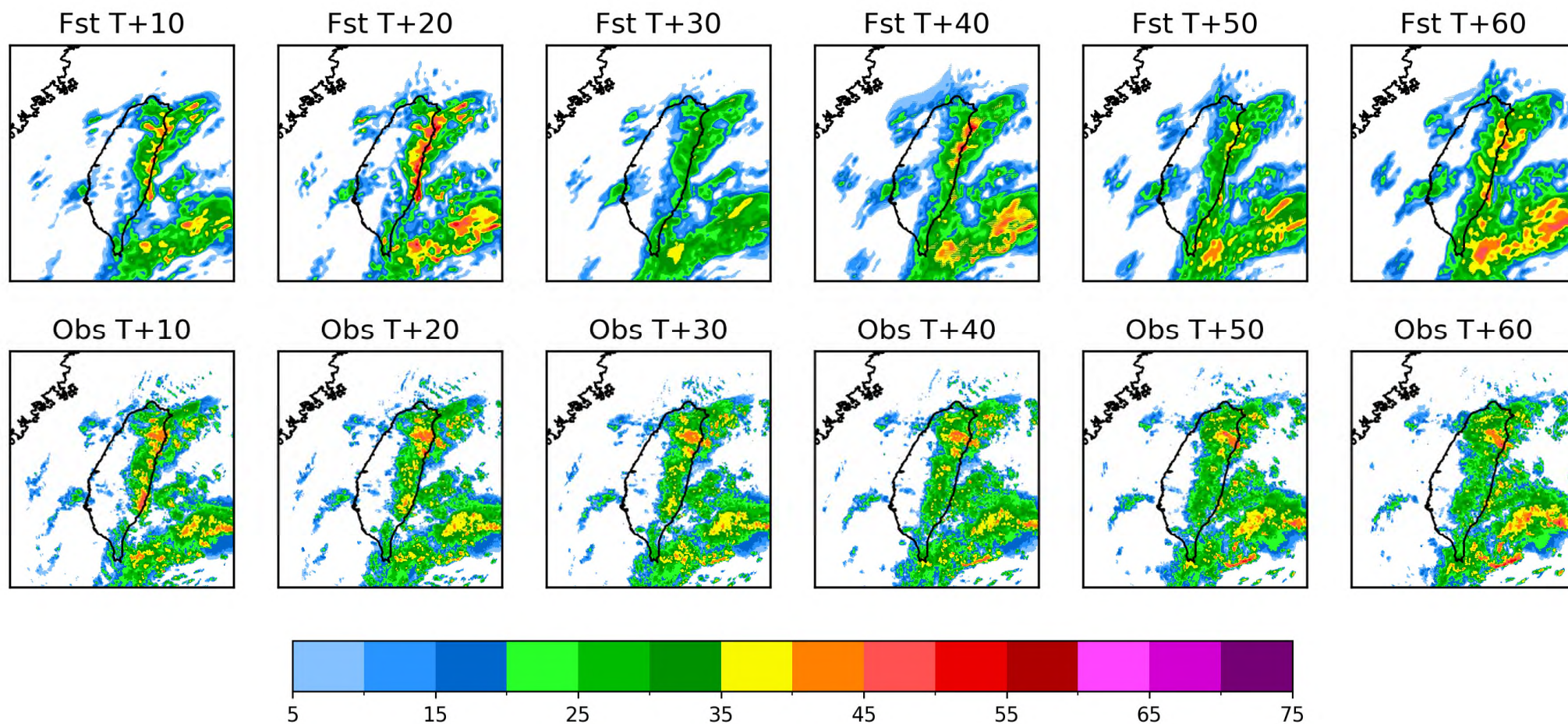
Results – Different clear sky threshold 10% area of 15 dBZ

./output_test4/y_COMPREF.OPENDATA.20221015.1800.gz.pt



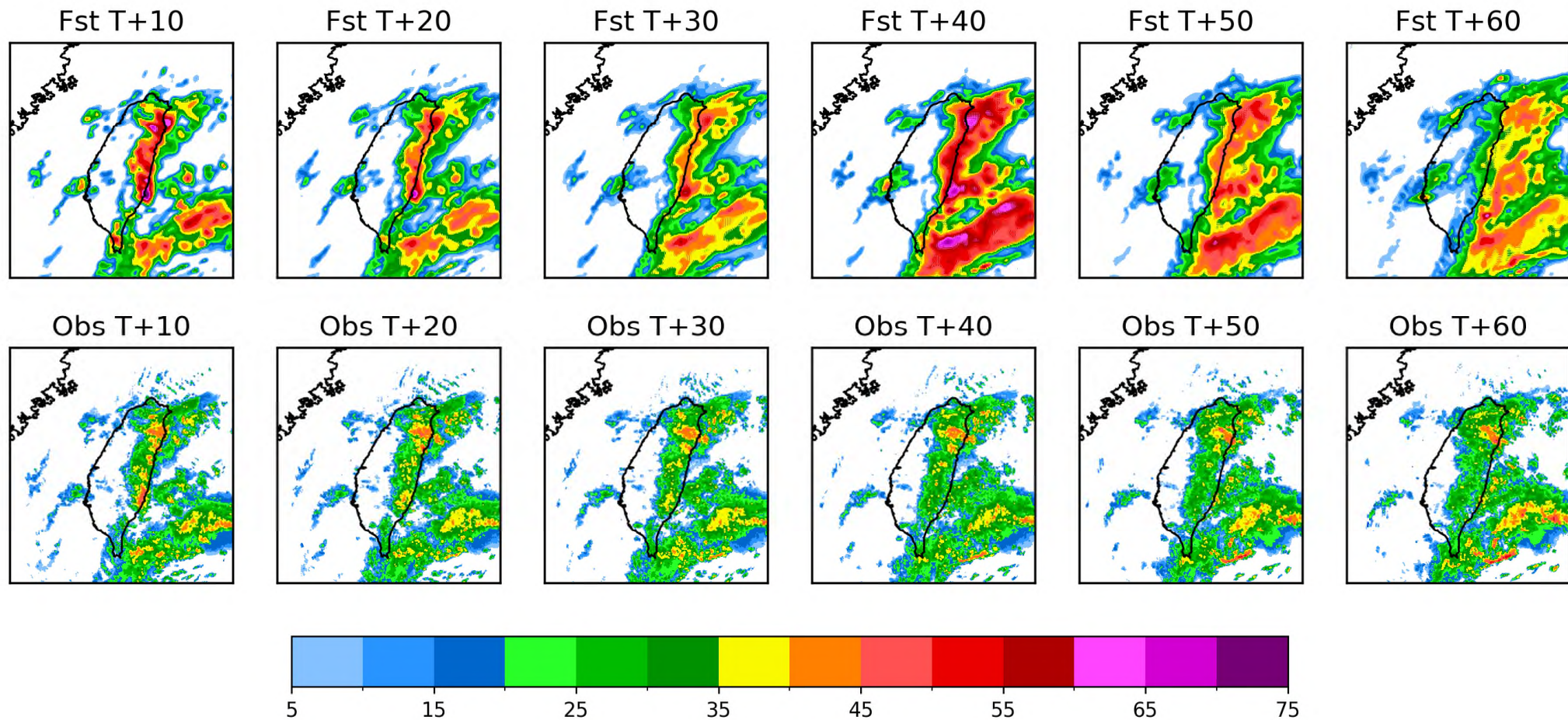
Results – Different clear sky threshold 15% area of 15 dBZ

./output_test6/y_COMPREF.OPENDATA.20221015.1800.gz.pt



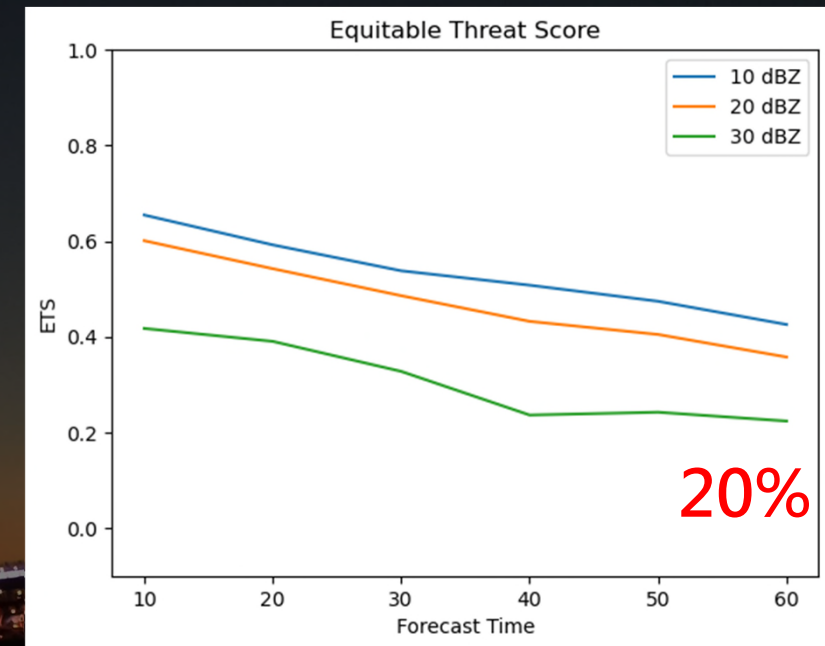
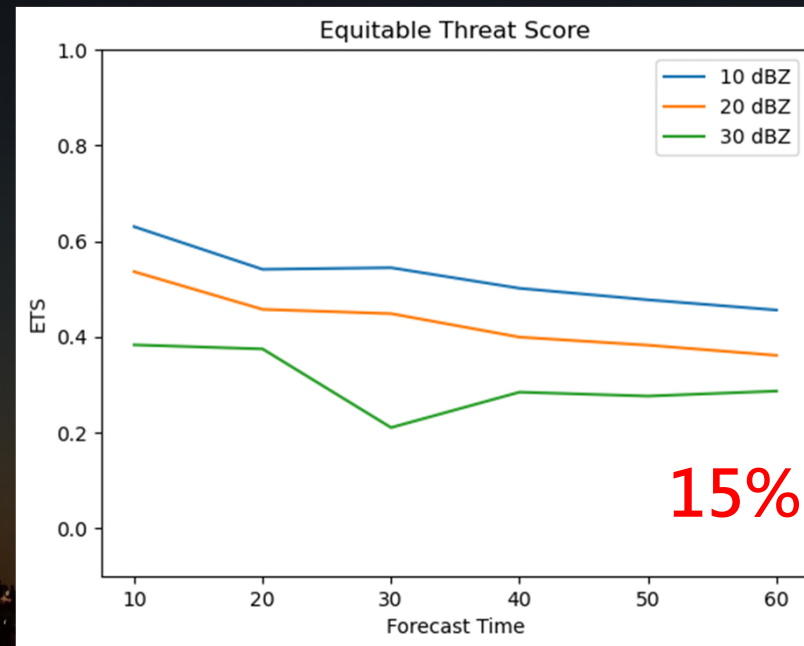
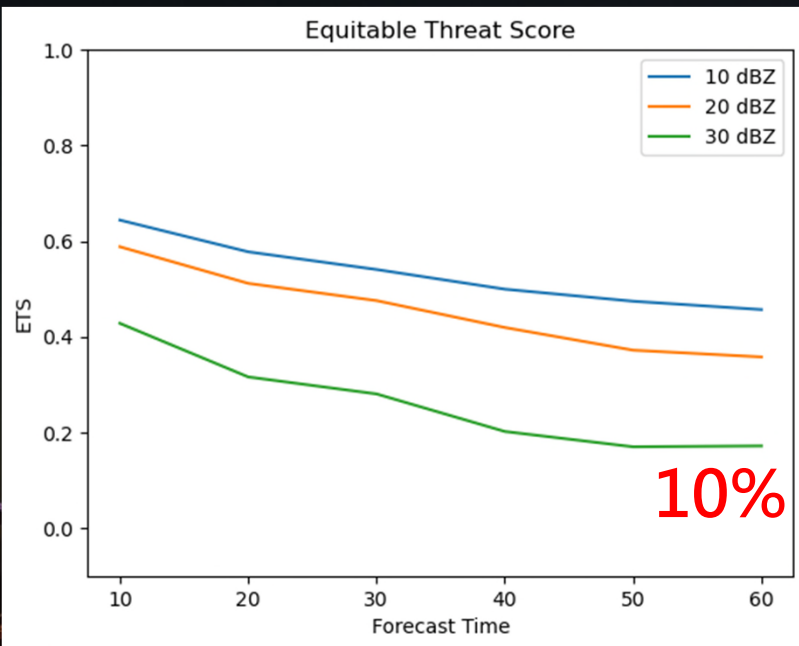
Results – Different clear sky threshold 20% area of 15 dBZ

./output_test3/y_COMPREF.OPENDATA.20221015.1800.gz.pt



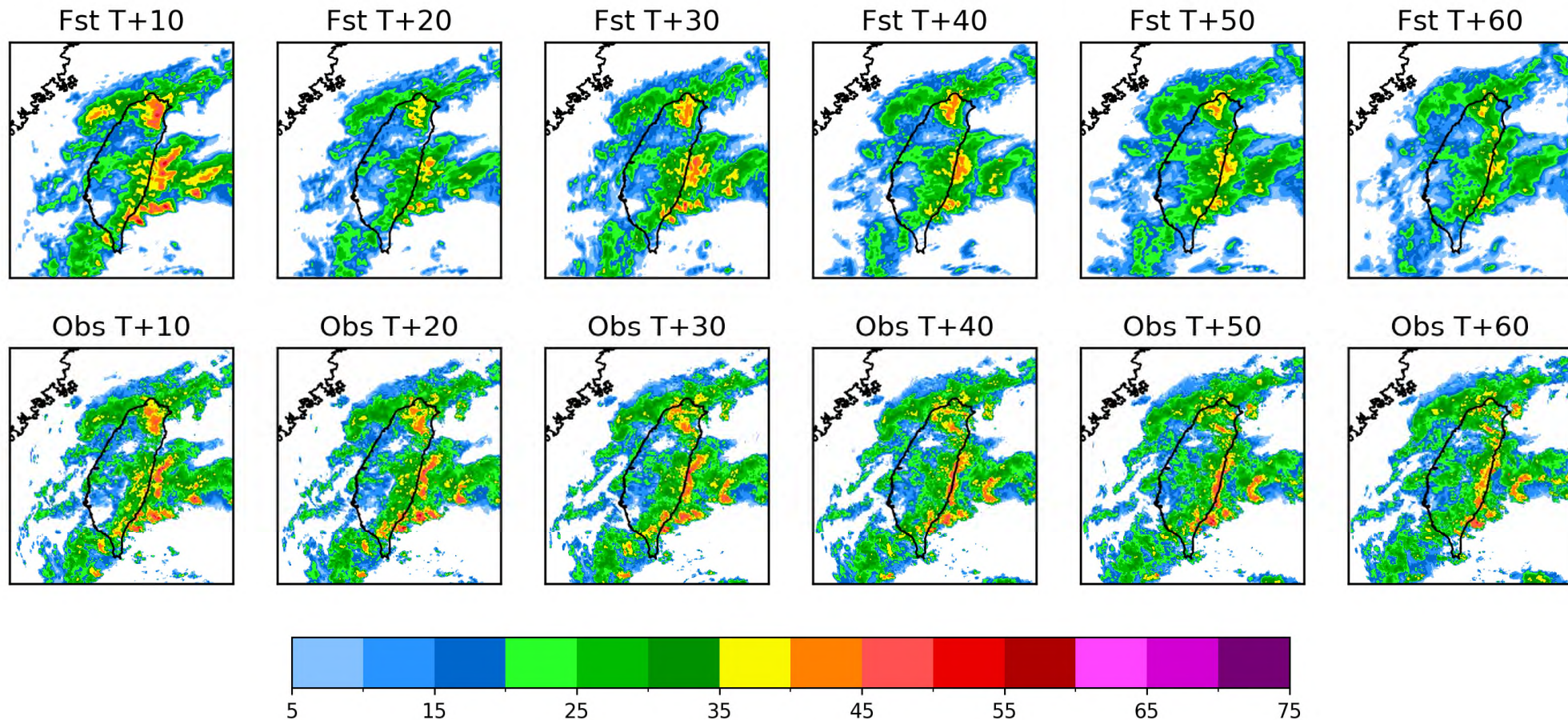
Results – Different clear sky threshold ETS

◇ 10% and 20% obviously poor in heavy rain



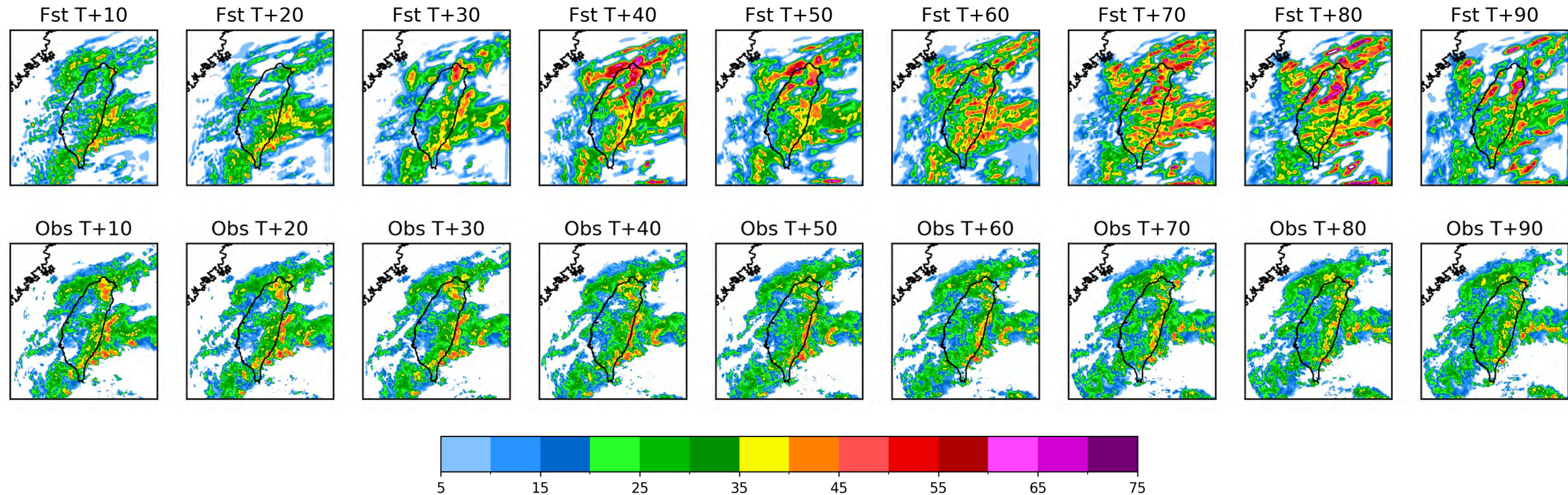
Results – Different input and output length 6 Obs, (60 min) → 6 Fst. (60 min)

./output_test11/y_COMPREF.OPENDATA.20221015.2140.gz.pt



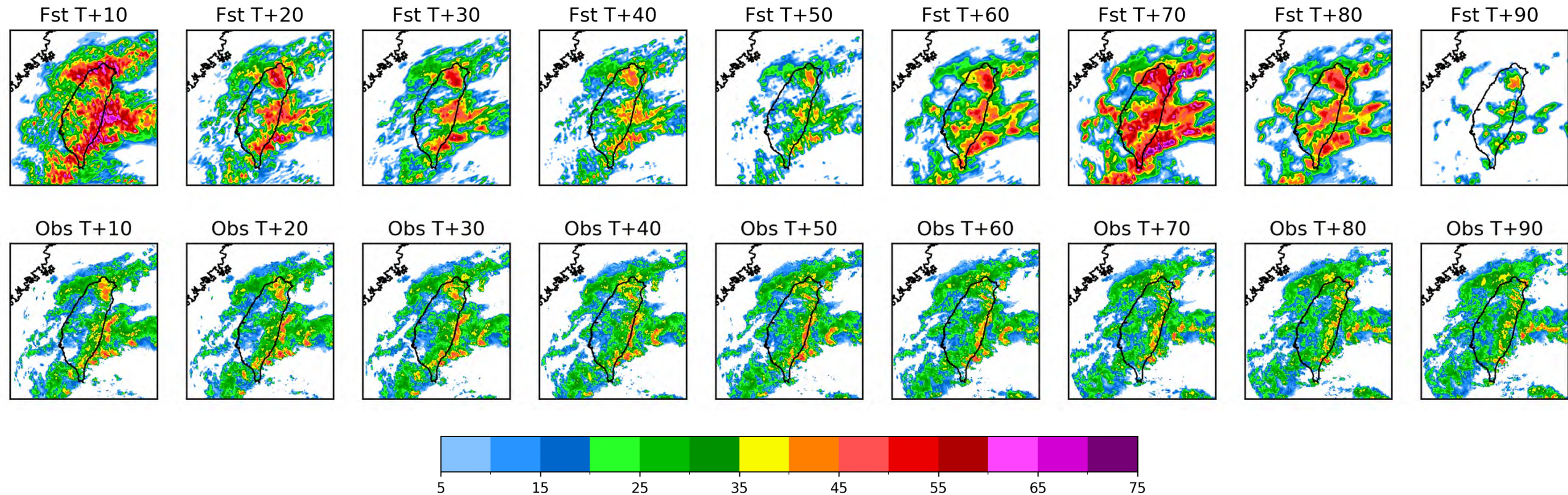
Results – Different input and output length 6 Obs, (60 min) → 9 Fst. (90 min)

./output_test10/y_COMPREF.OPENDATA.20221015.2140.gz.pt



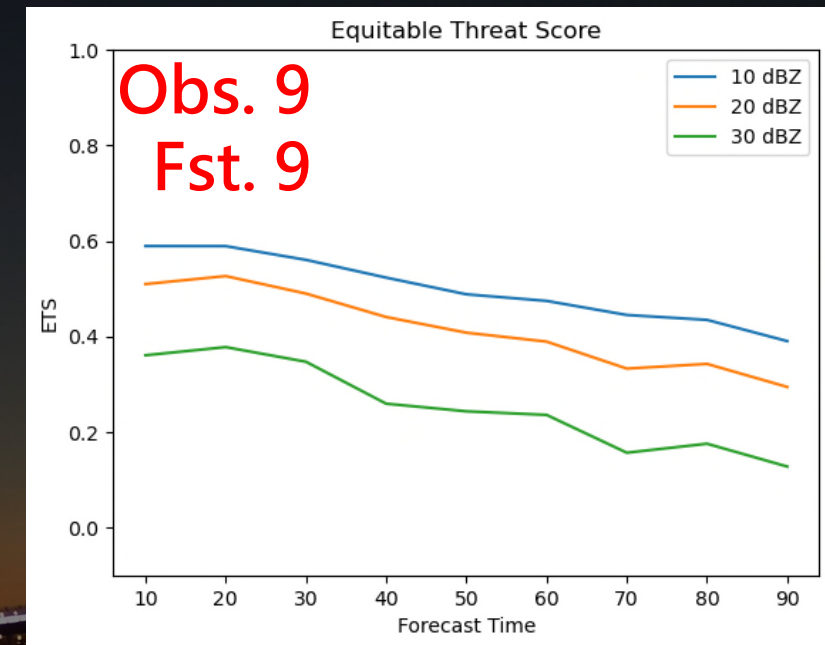
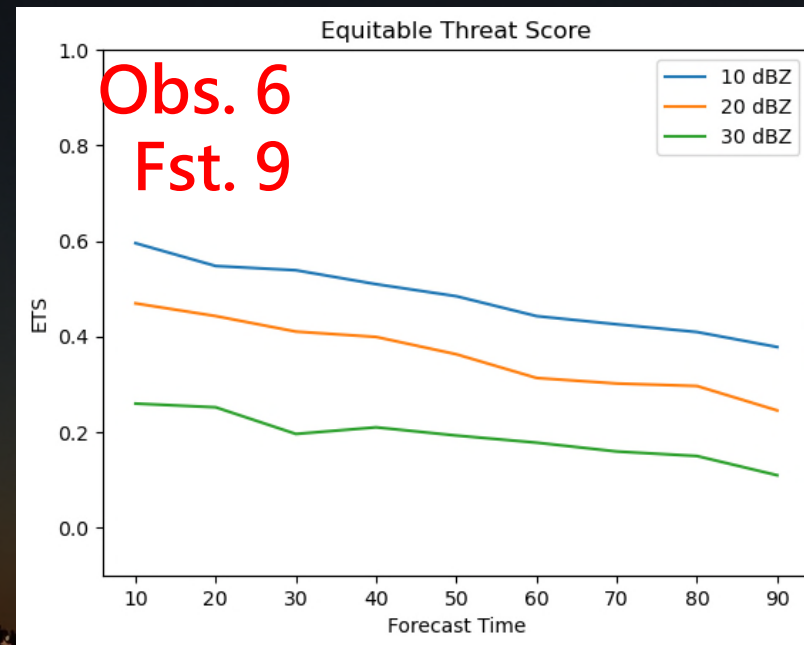
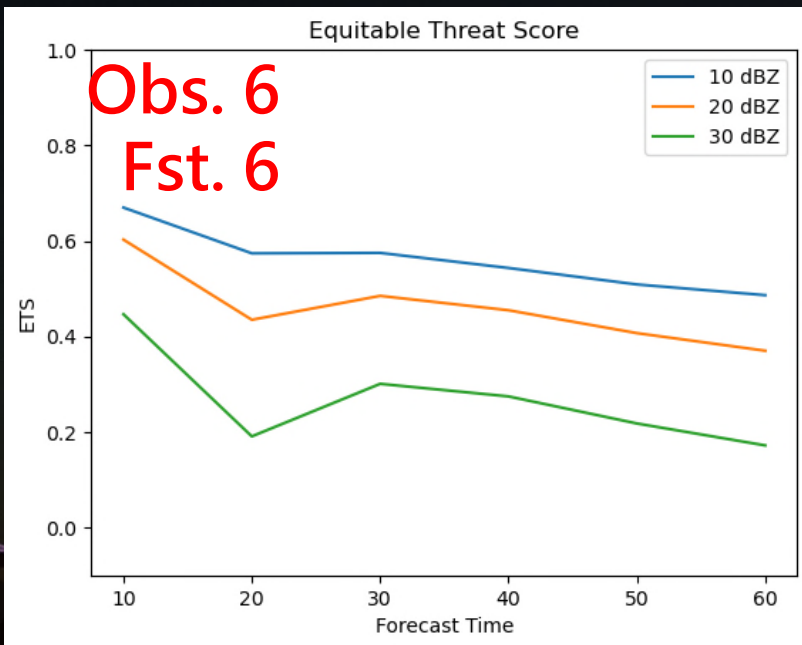
Results – Different input and output length 9 Obs, (90 min) → 9 Fst. (90 min)

./output_test9/y_COMPREF.OPENDATA.20221015.2140.gz.pt



Results – Different input and output length ETS

◇ 6-to-6 get highest ETS

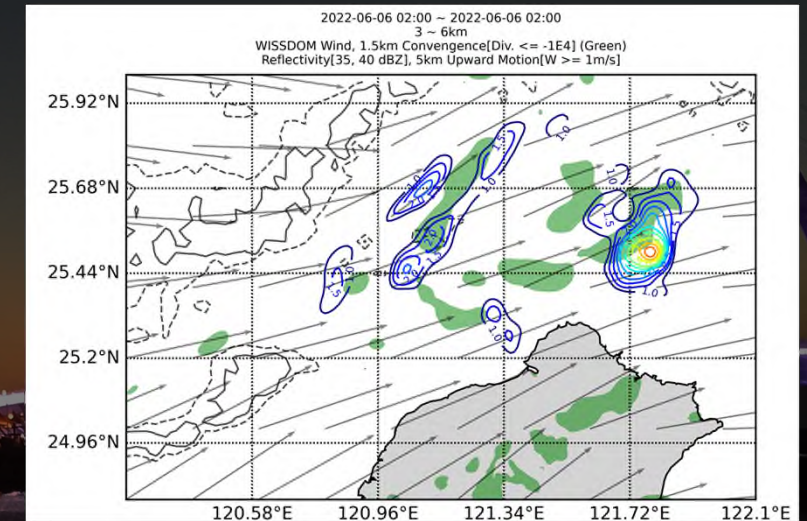
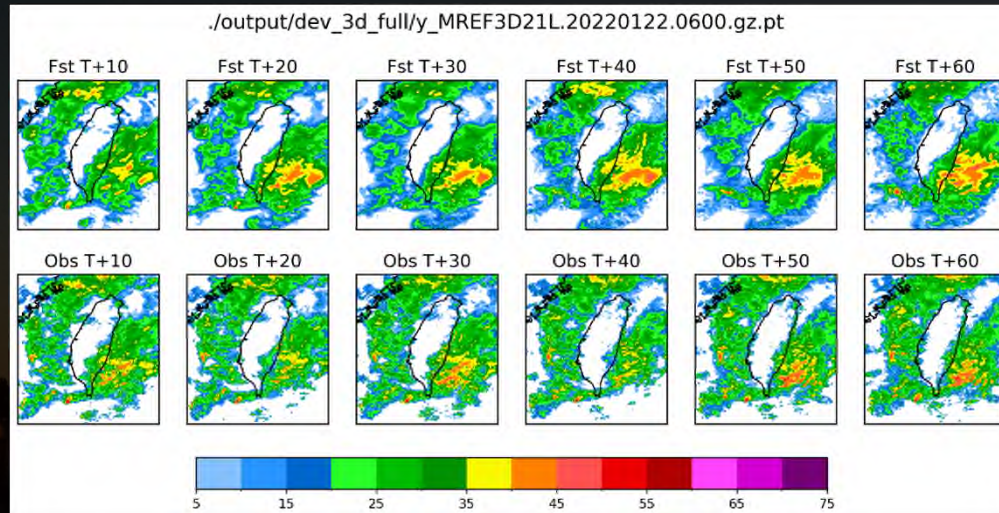


Summary

1. 15% area of 15dBZ is a suitable clear sky threshold in winter.
2. Higher clear sky threshold may cause insufficient training data; lower threshold may cause under-forecast.
3. Input 60 min. observed, and output 60 min. forecast is the best choice. This may be caused by only reflectivity cannot provide sufficient growth and decay information.

Future work

1. Test clear sky threshold in different season
2. More training data (many years)
3. 3D reflectivity input
4. Process-based (wind, vorticity, divergence...)



Reference

- Pan, X., Y. Lu, K. Zhao, H. Huang, M. Wang, and H. Chen, 2021: Improving Nowcasting of Convective Development by Incorporating Polarimetric Radar Variables Into a Deep-Learning Model. *Geophysical Research Letters*, 48, e2021GL095302, <https://doi.org/10.1029/2021GL095302>.
- Lin, K.-C., W.-T. Chen, P.-L. Chang, Z.-Y. Ye, and C.-C. Tsai, 2024: Enhancing the Rainfall Forecasting Accuracy of Ensemble Numerical Prediction Systems via Convolutional Neural Networks. *Artificial Intelligence for the Earth Systems*, 3, 230105, <https://doi.org/10.1175/AIES-D-23-0105.1>.

Thanks for your attention!